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KCT: a MATLAB toolbox for motion control of KUKA robot ...

KCT: a MATLAB toolbox for motion control of KUKA robot manipulators Francesco Chinello, Stefano Scheggi, Fabio Morbidi, Domenico Prattichizzo Abstract The Kuka Control Toolbox (KCT) is a collection of MATLAB functions for motion control of KUKA robot manipulators, developed to offer an intuitive and high-level programming interface to the user

An advertisement for Kuka robotics: can these machines ...

recherche sur le développement), Berenson is part of an experiment underway at the Quai Branly museum since 2012 The strangeness of the encounter with Berenson leaves you suddenly frightened, and you step back, away from the machine The uncanny valley This feeling has been explored in robotics since the 1970s, when Japanese researcher Professor

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Joint Stiffness Identification of a Heavy Kuka Robot with ...

Joint Stiffness Identification of a Heavy Kuka Robot with a Low-cost Clamped End-effector Procedure A Jubien^{1,2}, G Abba³ and M Gautier¹ 1IRCCyN (Institut de Recherche en Communications et

Einführung KUKA Roboter GmbH

Einführung KUKA Roboter GmbH Dr Johannes Kurth 44 Sitzung FA 413 Steuerung und Regelung von Robotern 26 Januar, 2011

La robotica industriale in Italia

KUKA Robotics Corp KUKA Development Laboratories, Inc Germany KUKA Roboter GmbH KUKA SysTec GmbH KUKA ProTec GmbH KUKA InnoTec GmbH AMATEC Robotics GmbH Le Innovazioni di Kuka 1985 Primo Robot Articolato 1996 Sviluppo di un teach pendant con HMI PC-based MS Windows 95 -> MS Windows XP 1998

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Trajectory planning and control for robot manipulations

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Creating Robot Models for MPK - A Rough Guide

Creating Robot Models for MPK - A Rough Guide Sagar Behere behere@kth.se August 2, 2009 Abstract This document summarizes the steps I took to create a robot model for the 6 DOF KUKA KR5 Sixx R850 robotic arm 1 Introduction Robot models for use with the MPK library need to have a collision model in Open Inventor's iv le format

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A PPP in European Robotics (Current business and technological trends in robotics, presentation of potential funding areas to be covered in the PPP) Rainer Bischoff KUKA Laboratories GmbH Avenue de Beaulieu 25 Brussels 19 September 2012

Experimental Results for Kuka Repeatability Measures and ...

Experimental Results for Kuka Repeatability Measures and Comparison with the Stochastic Ellipsoid Approach Jean-François Brethé, Eric Vasselín, Dimitri Lefebvre and Brayima Dakyo Groupe de Recherche en Electrotechnique et Automatique du Havre (GREA) UFR Sciences et Techniques, Université du Havre, BP540, 76058 Le Havre, France

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34 KUKA Robots[2] KUKA provides six axis robot systems These systems are further extendible by linear axes like rails Also the new KR C4 controller allows communication with a frequency up to 250[Hz] KUKA Ethernet KRL XML makes it possible to set up an anticyclic Ethernet link between a robot controller and up to nine external systems

Real-time Robot-assisted Ergonomics

that is ergonomically most comfortable for the interacting user Hence, human-robot interaction is continuously re-evaluated optimizing ergonomics states The approach is validated through an experimental study, based on established ergonomic methods and their adaptation for real

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